

Active Learning of Sequential Transducers with Side Information about the Domain

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1 Introduction

2 Existing Results

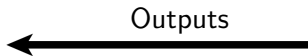
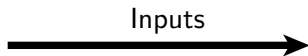
3 Graybox Subsequential Transducer Learning

Active Learning

Learning goal

Queries

Black box

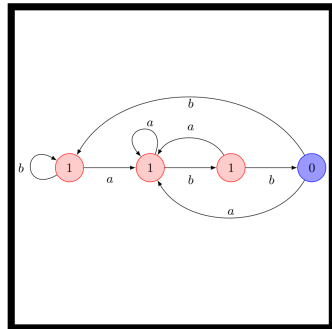
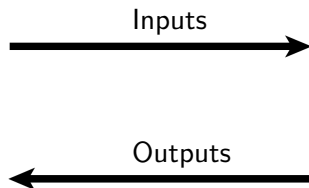


Regular Language Learning

Learn the
automaton

- Word membership
- Equivalence

DFA

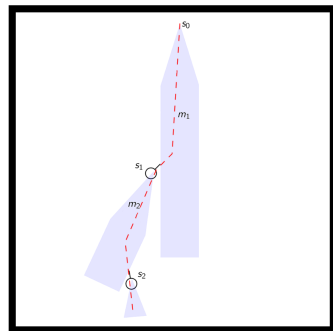
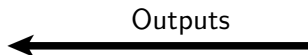
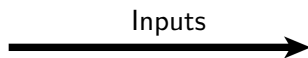
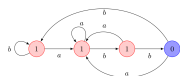


Motivation

Learn an implemented strategy while knowing the game structure

Queries

Strategy

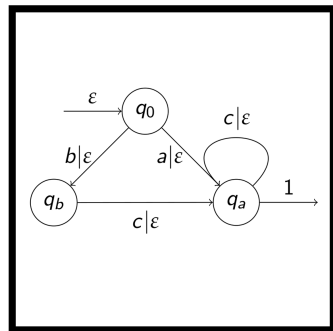
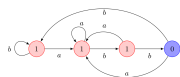
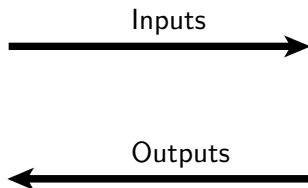


Graybox Subsequential Transducer Learning

Learn a transducer using side information

- Output of a word
- Equivalence

Transducer



Main result

Given a blackbox transduction τ and a domain upper-bound Up , our algorithm learns a transducer M of minimal size n such that $M|_{Up} = \tau$.

- Number of membership queries before a call to the SAT-solver:
POLY(n)
- Number of calls to the SAT-solver before an equivalence query:
EXP(n)
- Number of equivalence queries: n

1 Introduction

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Regular Language Learning

$L \subseteq \Sigma^*$ is an unknown regular language.

- Membership queries: does $u \in L$?
- Equivalence queries: is $\mathcal{L}(M) = L$?

Objective

Find an automaton M such that $\mathcal{L}(M) = L$.

Regular Language Learning

Let $P = S = \{\varepsilon\}$ and $T(P, S)$ the associated table

while *True* **do**

if *$u \cdot a \cdot v$ is a witness of non-consistency* **then**

 add *av* to *S*

else if *ua is a witness of non-closure* **then**

 add *ua* to *P*

else

$M := \text{Generate Automaton}(T(P, S))$

if *u is a non-equiv. witness for M* **then**

 add all its suffixes to *S*

else

 return *M*

Regular Language Learning

	ε	c
ε	0	0
a	1	1

The L^* algorithm uses membership queries to fill a table. Two lines represent the same state if they are equal.

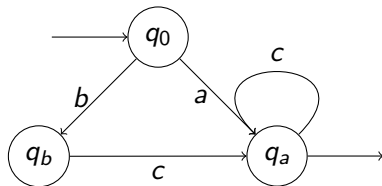
Regular Language Learning

	ε	c
ε	0	0
a	1	1
b	0	1

The L^* algorithm uses membership queries to fill a table. Two lines represent the same state if they are equal.

Regular Language Learning

	ε	c
ε	0	0
a	1	1
b	0	1
ac	1	1
bc	1	1



The L^* algorithm uses membership queries to fill a table. Two lines represent the same state if they are equal. Once there exists a unique automaton of minimal size compatible with this table, the algorithm makes an equivalence query.

Subsequential Transducer Learning

$\tau : \Sigma^* \rightarrow \Gamma^*$ is an unknown regular transduction.

- Membership queries: what is the output of u by τ ?
- Equivalence queries: is $\mathcal{L}(M) = \tau$?

Objective

Find a transducer M such that $\mathcal{L}(M) = L$.

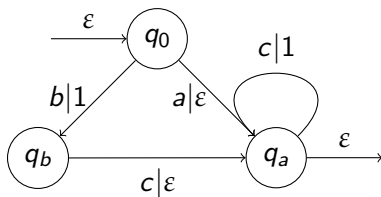
Subsequential Transducer Learning

	ε	c
ε	\perp	\perp
a	ε	1
b	\perp	1
ac	1	11
bc	1	11

When learning transducers, the *largest common prefix* of every line is factored out before building the candidate transducer.

Subsequential Transducer Learning

	ϵ	c
$\epsilon \epsilon$	\perp	\perp
$a \epsilon$	ϵ	1
$b \epsilon$	\perp	1
$ac 1$	ϵ	1
$bc 1$	ϵ	1



When learning transducers, the *largest common prefix* of every line is factored out before building the candidate transducer.

Graybox Regular Language Learning

$L \subseteq \Sigma^*$ is an unknown regular language.

Up is a known regular language.

- Membership queries: does $u \in L$?
- Equivalence queries: is $\mathcal{L}(M) \cap Up = L$?

Objective

Find an automaton M such that $\mathcal{L}(M) \cap Up = L$.

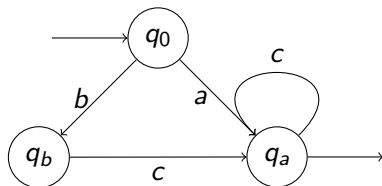
Graybox Regular Language Learning

	ε	c
ε	0	0
a	1	#
b	0	1
ac	#	#
bc	1	#

When learning a regular language in a *graybox setting*, a SAT-solver is used to find values for the # leading to a table associated to an automaton.

Graybox Regular Language Learning

ε	0
a	1
b	0
c	0
ac	$\# \leftarrow 1$
bc	1
acc	$\# \leftarrow 1$
bcc	$\# \leftarrow 1$



When learning a regular language in a *graybox setting*, a SAT-solver is used to find values for the $\#$ leading to a table associated to an automaton. It is sufficient to consider individual input words, and add the relations between them as equations in the solver.

1 Introduction

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3 **Graybox Subsequential Transducer Learning**

Graybox Subsequential Transducer Learning

$\tau : \Sigma^* \rightarrow \Gamma^*$ is an unknown regular transduction.

U_P is a known regular language.

- Membership queries: what is the output of u by τ ?
- Equivalence queries: is $\mathcal{L}(M)|_{U_P} = \tau$?

Objective

Find a transducer M such that $\mathcal{L}(M)|_{U_P} = L$.

Graybox Subsequential Transducer Learning

	ε	c
ε	\perp	\perp
a	ε	$\#$
b	\perp	1

Difficulty

When learning a transducer in a graybox setting, we must guess values for the $\#$ while keeping a finite search space.

Let $P = S = \{\varepsilon\}$ and $T(P, S)$ the associated table

while *True* **do**

if $u \cdot a \cdot v$ *is a witness of non-consistency* **then**

 add av to S

else if ua *is a witness of non-closure* **then**

 add ua to P

 ???

else

$M := \text{Generate Transducer}(T(P, S))$

if u *is a non-equiv. witness for* $Up \times M$ **then**

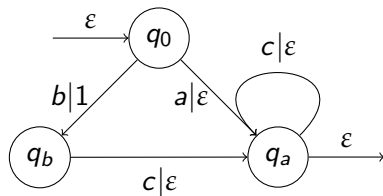
 add all its suffixes to S

else

 return M

Merging Map

Input	Output	Partial output
$\varepsilon \in [\varepsilon]$	ε	ε
$a \in [a]$	ε	ε
$b \in [b]$	\perp	1
$c \in [c]$	\perp	\perp
$ac \in [a]$	$\#$	ε
$bc \in [a]$	1	1

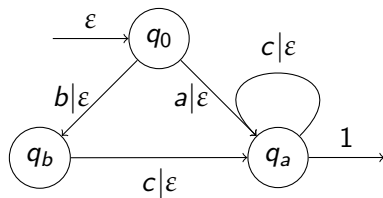


A *merging map* consists in guessing an equivalence class and a partial output for every input.

We define the transducer resulting from a given merging map.

Merging Map

Input	Output	Partial output
$\epsilon \in [\epsilon]$	ϵ	ϵ
$a \in [a]$	ϵ	ϵ
$b \in [b]$	\perp	ϵ
$c \in [c]$	\perp	\perp
$ac \in [a]$	$\#$	ϵ
$bc \in [a]$	1	ϵ



Different merging maps may lead to different resulting transducers, but there exists a finite number of merging maps associated to a given table.

Let $P = S = \{\varepsilon\}$ and $T(P, S)$ the associated table

while *True* **do**

if $u \cdot a \cdot v$ *is a witness of non-consistency* **then**

 add av to S

else if ua *is a witness of non-closure* **then**

 add ua to P

else if u *distinguishes two merging maps* **then**

 add u and its suffixes to S

 ???

else

$M := \text{Generate Transducer}(T(P, S))$

if u *is a non-equiv. witness for* $Up \times M$ **then**

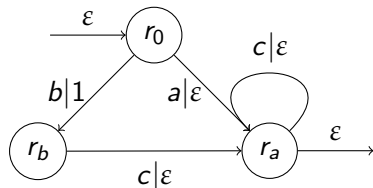
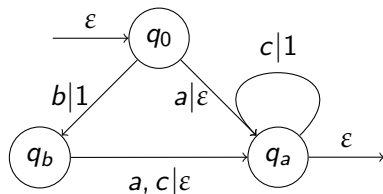
 add all its suffixes to S

else

 return M

Merging Map

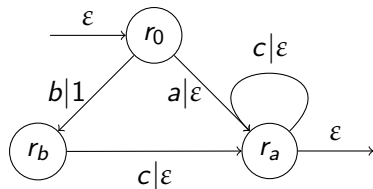
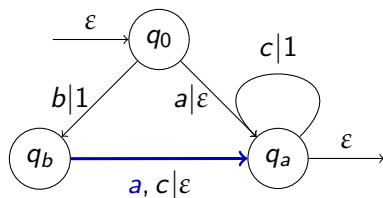
Input	Output	Partial output
$\varepsilon \in [\varepsilon]$	ε	ε
$a \in [a]$	ε	ε
$b \in [b]$	\perp	ε
$c \in [c]$	\perp	\perp
$ac \in [a]$	$\#$	ε
$bc \in [a]$	1	1



A merging maps may be induced by a transducer that is not equivalent to the resulting transducer of this merging map.

Merging Map

Input	Output	Partial output
$\varepsilon \in [\varepsilon]$	ε	ε
$a \in [a]$	ε	ε
$b \in [b]$	\perp	ε
$c \in [c]$	\perp	\perp
$ac \in [a]$	$\#$	ε
$bc \in [a]$	1	1



An open transition may be removed without changing the behaviour on the table.

Let $P = S = \{\varepsilon\}$ and $T(P, S)$ the associated table

while *True* **do**

if $u \cdot a \cdot v$ is a witness of non-consistency **then**

 add av to S

else if ua is a witness of non-closure **then**

 add ua to P

else if u distinguishes two merging maps **then**

 add u and its suffixes to S

else if u uses an open transition **then**

 add u and its suffixes to S

 ???

else

$M := \text{Generate Transducer}(T(P, S))$

if u is a non-equiv. witness for $Up \times M$ **then**

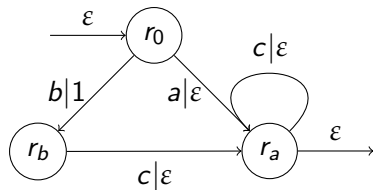
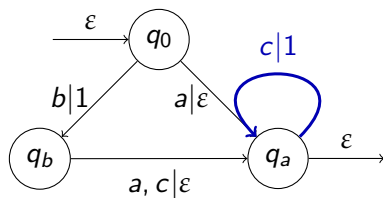
 add all its suffixes to S

else

 return M

Merging Map

Input	Output	Partial output
$\varepsilon \in [\varepsilon]$	ε	ε
$a \in [a]$	ε	ε
$b \in [b]$	\perp	ε
$c \in [c]$	\perp	\perp
$ac \in [a]$	$\#$	ε
$bc \in [a]$	1	1



A muted transition may have an output of ε without changing the behaviour on the table.

Let $P = S = \{\varepsilon\}$ and $T(P, S)$ the associated table

while *True* **do**

if $u \cdot a \cdot v$ *is a witness of non-consistency* **then**

 add av to S

else if ua *is a witness of non-closure* **then**

 add ua to P

else if u *distinguishes two merging maps* **then**

 add u and its suffixes to S

else if u *uses an open transition* **then**

 add u and its suffixes to S

else if u *uses a muted transition* **then**

 add u and its suffixes to S

else

$M := \text{Generate Transducer}(T(P, S))$

if u *is a non-equiv. witness for* $Up \times M$ **then**

 | add all its suffixes to S

else

 | return M

Main result

Given a blackbox transduction τ and a domain upper-bound U_p , our algorithm learns a transducer M of minimal size n such that $M|_{U_p} = \tau$.

- Number of membership queries before a call to the SAT-solver:
POLY(n)
- Number of calls to the SAT-solver before an equivalence query:
EXP(n)
- Number of equivalence queries: n

Future works

- Better Evaluation of the number of calls to a SAT-solver.
- Work on an implementation.